# 1 - Algebraic Preliminaries

#### Exercise 4 (page 85)

Since  $\dim(\Lambda^n(\mathbb{R})) = 1$ , and since  $\omega \in \Lambda^n(V)$  implies that  $f^*\omega \in \Lambda^n(\mathbb{R}^n)$ , we know that  $f^*\omega = c$  det for some  $c \in \mathbb{R}$ . To find out c, we evaluate this equation at  $(e_1, \ldots, e_n)$ :

$$f^*\omega(e_1,\ldots,e_n) = c \det \begin{pmatrix} e_1 \\ \vdots \\ e_n \end{pmatrix} = c$$

or

$$\omega(f(e_1),\ldots,f(e_n))=c$$

Applying Theorem 4-6, we get

$$det(a_{ij}) \cdot \omega(v_1, \dots, v_n) = c$$

where  $\{v_i\}_{i=1}^n$  is a basis for v and the  $a_{ij}$  are defined by  $f(e_i) = \sum_{j=1}^n a_{ij}v_j$ . By hypothesis,  $[f(e_1), \ldots, f(e_n)] = \mu$  so that  $\det(a_{ij}) = 1$ . Also, since  $\omega$  is the volume element w.r.t.  $\mu$  and T, we get  $\omega(v_1, \ldots, v_n) = 1$ , so we conclude c = 1. Thus  $f^*\omega = \det$  follows.

## 4 - The Fundamental Theorem of Calculus

### **Exercise 29** (page 105)

To show existence, define  $\lambda = \int \omega = \int_0^1 f dx$ , and  $g(x) = \int_0^x f dx - \lambda x$ . By Theorem 4-7, we calculate  $dg = Dg \cdot dx$ .  $Dg = f - \lambda$ , so  $dg = \omega - \lambda dx$  follows. Also note that  $g(0) = \int_0^0 f dx - \lambda \cdot 0 = 0$ , and  $g(1) = \int_0^1 f dx - \lambda = \int_0^1 f dx - \int_0^1 f dx = 0$ , so g(0) = g(1) = 0.

To show uniqueness, suppose that  $\omega - \lambda dx = dg$ , where g(0) = g(1). Integrating, we get

$$\int_0^1 \omega - \lambda = \int_0^1 dg$$

By Stoke's theorem, we have  $\int_0^1 dg = g(1) - g(0) = 0$ , so  $\lambda = \int_0^1 \omega = \int_0^1 f dx$ . So the  $\lambda$  is completely determined by f, and is thus *unique*.

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Calculus on Manifolds – Spivak

### Exercise 34 (page 108)

(a) Following the definitions, we have

$$\partial C_{F,G} = -(C_{F,G})_{(1,0)} + (C_{F,G})_{(1,1)} + (C_{F,G})_{(2,0)} - (C_{F,G})_{(2,1)} - (C_{F,G})_{(3,0)} + (C_{F,G})_{(3,1)}$$
 where

$$(C_{F,G})_{(1,0)}(u,v) = C_{F,G}(0,u,v) = F(0,u) - G(0,v) = C_{F_0,G_0}(u,v)$$

$$(C_{F,G})_{(1,1)}(u,v) = C_{F,G}(1,u,v) = F(1,u) - G(1,v) = C_{F_1,G_1}(u,v)$$

$$(C_{F,G})_{(2,0)}(s,v) = C_{F,G}(s,0,v) = F(s,0) - G(s,v)$$

$$(C_{F,G})_{(2,1)}(s,v) = C_{F,G}(s,1,v) = F(s,1) - G(s,v)$$

$$(C_{F,G})_{(3,0)}(s,u) = C_{F,G}(s,u,0) = F(s,u) - G(s,0)$$

$$(C_{F,G})_{(3,1)}(s,v) = C_{F,G}(s,u,1) = F(s,u) - G(s,1)$$

Since each  $F_s$  is closed, i.e. F(s,0) = F(s,1), for all s, we see that  $(C_{F,G})_{(2,0)} = (C_{F,G})_{(2,1)}$ .

Similarly, since each  $G_s$  is closed,  $(C_{F,G})_{(3,0)} = (C_{F,G})_{(3,1)}$ . Thus, the only surviving terms of  $\partial C_{F,G}$  are those due to  $(C_{F,G})_{(1,0)}$  and  $(C_{F,G})_{(1,1)}$ . So  $\partial C_{F,G} = C_{F_1,G_1} - C_{F_0,G_0}$  follows.

(b) If  $d\omega = 0$  then by (a) and Theorem 4-13 (Stoke's theorem), we get

$$0 = \int_{C_{F,G}} d\omega = \int_{\partial C_{F,G}} \omega = \int_{C_{F_1,G_1}} \omega - \int_{C_{F_0,G_0}} \omega$$

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so we conclude  $\int_{C_{F_1,G_1}} \omega = \int_{C_{F_0,G_0}} \omega$ .